Impact of surface choking on gas-lift stability and flow behaviour in oil producing wells

Abstract: In this work, we investigate the effect of tubing head choking on gas-lift stability and flow regime transition in the vertically upward cylindrical pipe during gas-lift operation. For this purpose, a laboratory scale multiphase flow rig was designed, fabricated and assembled. Lift gas injection rates of $1.13 \times 10^{-4} \text{m}^3/\text{s}$ and $1.87 \times 10^{-4} \text{m}^3/\text{s}$ were imposed in a 1 mm internal diameter (ID) single nozzle gas-lift injector connected to a rotameter and a liquid flow rate of $7.7 \times 10^{-6} \text{m}^3/\text{s}$ was set in a speed potentiometer connected to a positive displacement gear pump. Tubing head choking is implemented by setting the system to 0% closed (fully opened) to partially closed – 15%, 25% and 50% opened (85%, 75% and 50% choking). For each choking condition, the transient pressure at four measurement points located at length to diameter ratios $L/D$ of 0.0; 18.3; 36.7, and 53.3 was recorded. Fluid flow structure and regime transition are distinguished and characterised based on the visual observations, photographic and slow motion videos, recorded for every single cycle of experiment run in the production test sections from $L/D = 18.3$ to $L/D = 53.3$. It was found that increasing the choke up to 85%, a transition from random peak-to-peak oscillation of pressure to a cyclic periodic oscillation is observed and this behaviour is accompanied with increase in pressure along the production tubing. The effect of topside choking on bubble size showed a drastic reduction of the size of the leading bubble as it flows upwards with a maximum perimeter of 35.65 mm the flow is characterised by low vorticity and turbulence of the liquid film when the choke is increased up to 85%. Based on the experimental results, the topside coking technique as flow stabiliser during gas-lift operations has to be conjugated with knowledge and understanding of fluid flow structure transition along the production tubing.

Keywords: Gas-lift; Multiphase flow, Instability, Fluid Flow Structure.
1 Introduction

Complex multiphase fluids containing oil, gas, water, and sometimes precipitated solids and or formation sands may flow through production tubing to the surface, with several flow regimes recorded. The natural lifting performance may be compromised as a result of this complex multiphase flow in the tubing (Brown, 1982; Clegg, 2007). As a result of the natural lifting decline, an artificial lift technique may be used to boost production. One of the approaches that could be used is gas-lift, which involves the injection of gas at high pressure into the tubing at specific spots to elevate the produced fluid from the wellbore to the surface (Rashid et al., 2012).

Normally, the gas is injected using a single valve attached to the pipe wall. The gas-liquid two-phase flow may result in a multiphase fluid structure such as bubble flow, churn flow, slug flow, and perhaps annular (Guet et al., 2003, 2004). The occurrence of fluid flow structure transition brings instabilities into the production tubing.

A group of authors (e.g. Bertuzzi et al. (1953); Gilbert (1954); Grupping et al. (1984); Xu and Golan (1989)) described gas-lift instability as a phenomenon that periodically stops the oil flow and causes vibrations that damage downhole and surface facilities. This instability can occur for a variety of reasons including gas cusping or water coning; the accumulation of water, oil or condensates in the pipeline (slugging); or increased pressures in the well (Chia and Hussain (1999); Jansen et al. (1999); Abdin (2000); Ranjan et al. (2015).)

Some of the methods currently used in stabilising wells include wellhead choking; increasing gas injection beyond optimum rate; reducing the injection valve port size and use of feedback control systems. Clift et al. (2005) observed that if the bubbles are smaller, the rising velocity will be reduced, resulting in reduction of gas velocity, increase of void fraction, and reduction of hydrostatic head term of the total pressure drop.

Some authors (e.g. Eikrem et al. (2008); Jahanshahi et al. (2008b,a,c, 2009)) argue that tubing head choking tends to increase the stability of gas-lifted wells. Others (e.g. Beadle (1963); Chia and Hussain (1999)) defend that choking a gas-lift well reduces gas-lift efficiency due to the additional surface back pressure being imposed on the system; consequently resulting in less liquid production rate and higher gas-lift gas injection requirements. Zhou et al. (2018) advocate the choking technique as a technique that minimises slug flow although, this has to be done with care in order to avoid losses in production.

Rodrigues and Almeida (2017) conducted an experimental investigation on the applicability of bubble-breakage devices inside the tubing. They used different bubble-breakers configurations namely plate, nozzle, and venturi with different inlet and outlet geometries. A 20% reduction in pressure was achieved in some cases, but in other cases, localised pressure losses were generated. They concluded that the bubble-breaker testes were not effective for slug flow and several aspects of the bubble-breaking processes are not well understood. The use of bubble-breakers is limited due to gas-liquid fluid flow structure reconstruction after passing through the bubble-breakers.

The applicability of the techniques such as injecting gas-lift gas at a high flow rate; reduction of surface choke size, controlling the sizes of bubbles, and use of venturi nozzle (Guet et al. (2003); Eikrem et al. (2008); Sulaiman et al. (2019); Song et al. (1995); Tolkotter et al. (2016); Chiba and Takahashi (1998); Kawamura et al. (2004); Santos and Pinheiro (2014); Mayor et al. (2008); Iguchi et al. (1998); Jansen et al. (1996); Koide et al. (1968), may lead to increase in pressure losses due to friction in the tubing, redesign of integral mandrels, and injection at critical gas-lift gas injection flow rate. Additionally, it is impossible to guarantee the size of small bubbles along the production tubing height because of the expansion of bubbles as they rise (Santos and Pinheiro, 2014; Jansen et al., 1996). Chia and Hussain (1999), argued that choking a gas-lift well reduces gas-lift efficiency due to the additional surface back pressure, which results in less produced liquid rate and higher lift gas consumption.

1.1 Criteria for stability in relation to choking

Jansen et al. (1996), applied choke and gas-lift as methods of eliminating severe slugging. This investigation was carried out experimentally and theoretically and the following stability criteria was developed:

Jansen et al. (1996) applied choke and gas-lift as methods of eliminating severe slugging. This investigation was carried out experimentally and theoretically and the following stability criteria was developed:

\[ P_r + C U_{ls}^2 \geq \frac{\alpha L}{\kappa} \left( \Phi - \frac{K}{\rho g} \right) - \frac{P_s}{\rho g} \]

where, \( P_r \) denotes the average holdup in the riser, \( \rho_l \) is the liquid density, \( C \) is the choke coefficient, \( K \) proportionality constant, \( H \) is the riser height, \( U_{ls} \) is the liquid superficial velocity, \( P_0 \) and \( P_s \) denote the atmospheric pressure and pressure inside the separator tank; \( \alpha \) and \( \alpha' \) stand for gas void fraction and void fraction of gas front entering the liquid column. Equation 1 is a result of the force balance between the gas pressure force induced by the enlargement of the gas phase and the increment hydrostatic head, the pressure at the separator and the pressure drop at the choke (Jansen et al., 1996). The proposed stability criteria is based on the physical configuration of the test rig and its components and can not be generalised.

It was observed that both choking and lift gas eliminate slugging by the increment of the back pressure and increasing the amount of lift gas. The degree of stability achieved by increasing the lift gas might be associated with annular flow regime characterised by continuity of the gas phase along the tubing. Annular flow is distinguished by flow of gas and liquid separately (Sharaf et al., 2016; Kaji et al., 2009; Omebere-Iyari and Azzopardi, 2007). This flow regime is undesired in gas-lift operations because it is associated with the slippage and consequent increase in pressure drop due to friction caused by acceleration of the gas phase. Surface choking is a restriction in a flow line set by decreasing the injection valve port size and use of venturi nozzle at critical gas-lift gas injection flow rate; reduction of surface back pressure, which results in less produced liquid rate and higher lift gas consumption.
strategy for bringing wells to a stable operational condition. However, the consequences of the low-pressure region in the choke can lead to severe problems with cavitation and related flashing (vaporisation). The aforementioned techniques are relevant and in many cases adequate for many engineering calculations. Yet, there are specific cases of gas-lift operations where detailed information about the structure of the flow inside production tubing; particularly the slug characteristics during tubing head choking, is essential (Barnea and Taitel, 1993). Xie et al. (2017) observed devaluation of the slug region while increasing the backpressure while investigating slugging in multiphase flow. Reductions in pressure amplitude as well as the slug frequency, were also noticed. Battino et al. (1984) proposed the equation below equation 2 as a mean of estimation e the solubility of air in water. This equation advocates that the solubility of air in water at fixed temperature, increases with pressure.

\[ \ln S = -\frac{68.471}{\tau} + 19.316\ln \tau - 0.020613P + 1.1243\ln P \]

(2)

where, \( S \) is the solubility of air in \( \text{cm}^3/g(\text{STP}) \); \( \tau \) denotes \( T/1000 \), \( T \) is the temperature in \( K \) and \( P \) is absolute pressure in \( MPa \). In this work, topside choking is replicated experimentally in order to study its effect on gas-lift stability by (a) evaluating its impact on bottom hole pressure, operating valve pressure, unloading valve pressure, and tubing head pressure oscillations and (b) investigating its influence on fluid flow structure transition occurring along the production tubing. The influence of restringing the outlet flow conditions on the physical shape, size and distribution of the bubbles inside the production tubing were captured dynamically using high-speed camera. The experimental data obtained in this study provides a direct means of characterising flow regime and deriving relationship between surface choking and well stability in gas-lifted wells.

2 Methodology

In order to investigate the effect of surface choke on dynamic behaviour associated with gas lift instabilities, a pilot-scale rig was designed, fabricated, and assembled. The design of this facility is such that it allows for a wide range of two-phase flow conditions. Figure 1 is a 2 dimensional schematic of a geometrical representation of a gas-lift production system with an instrumentation diagram (P&ID). The test sections of the production tubing with pressure transducers and high-speed camera are shown in Figure 2.

Four choking configurations were imposed at the tubing head to analyse the flow regime and gas bubble dynamics in the production tubing. This is achieved by mounting a pressure regulator valve inline of the returning pipe connected to the top of the producing tubing (see Figure 1). The surface choke is implemented by setting the system to 0% closed (fully opened) to partially closed 15%, 25% and 50% opened (85%, 75% and 50% choking). For each choking condition, the transient pressure at four measurement points located at length to diameter ratios of \( (L/D=0.0; 18.3; 36.7; 53.3) \) was recorded as well as the fluid flow structure along the production tubing test sections. Gas-lift injection rates of \( 1.13e^{-4} \text{ m}^3/\text{s} \) and \( 1.87e^{-4} \text{ m}^3/\text{s} \) were imposed in a 1 mm internal diameter (ID) single nozzle gas-lift injector connected to a rotameter and a liquid flow rate of \( 7.7e^{-6} \text{ m}^3/\text{s} \) was set in a speed potentiometer connected to a positive displacement gear pump.

Figure 1 Process and instrumentation diagram P&ID of the multiphase flow rig

Figure 2 2D representation of the test sections of the production tubing with pressure transducers and high speed camera.

2.1 Instrumentation

Rotameter, pressure regulator, and gas flow regulator are used for monitoring and controlling the gas-lift injection rate, while an inverter frequency regulator with speed potentiometer is used to control the motor shaft rotational speed for setting the liquid flow rate from the water source tank into the test section during the experiments. In order to measure and record the transient pressure due to gas-lift at the bottomhole, operating valve, unloading valve, and production tubing, four pressure transducers reference \( PXM319 – 010G10V \), with a pressure
range of 0 – 10 bar were used to acquire transient pressure measurements at four points along with the production tubing. The first one is installed at the bottom of the tubing for acquiring the bottom hole pressure \( p_{bh} \) at \( L/D = 0.0 \), the second pressured transducer is installed at operating gas-lift valve (\( L/D = 18.3 \)), the third one is located at the unloading gas-lift valve at \( L/D = 36.7 \) and the fourth one is at the top of the producing tubing for reading and recording the tubing head pressure \( p_{th} \), \( L/D = 53.3 \) as shown in Figure 1. The pressure transducers are connected to a data acquisition system reference OM-USB108FS. Transient behaviour of pressure at bottomhole; operating valve, unloading valve, and at tubing head is recorded in real-time during gas-lift operation. The pressure transducers require a supply voltage of 24V to operate. For this, an electronic circuit device that converts a source of direct current (DC) from 5 voltage from the USB DAQ unit level to 24 voltage was installed.

### Table 1 Fluid physical properties (Shao et al., 2008) and initial conditions

<table>
<thead>
<tr>
<th>Flow rate ( \nu ) [m(^3)/s]</th>
<th>Density ( \rho ) [kg/m(^3)]</th>
<th>Viscosity ( \mu ) [Pa.s]</th>
<th>Tension ( \sigma ) [N/m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Water ( 7.7 \times 10^{-6} )</td>
<td>998</td>
<td>1.03e-4</td>
<td>0.07226</td>
</tr>
<tr>
<td>Air ( 1.25 \times 10^{-5} )</td>
<td>1.19</td>
<td>1.79e-4</td>
<td></td>
</tr>
</tbody>
</table>

### 2.2 Assumptions, boundary and initial conditions

The fluid flow is assumed to be incompressible, isothermal and mass transfer between the phases may occur at production tubing head due to cavitation of the liquid phase. The inlet flow rate of the liquid phase is placed at the bottom of the tubing (see Figure 1), while the gas-lift flow rate is set at lower side of the tubing (operating valve), (see Figure 1)

### 3 Results and Discussion

#### 3.1 Influence of choking at tubing head-on pressure instability

Gas-lift stability is evaluated on bottom hole pressure; operating valve pressure; unloading valve pressure and tubing head pressure. The range of tubing head choke is set in % of valve opening. The experiments were performed by closing the production choke from 0% closed (fully opened) to 85% closed (15% opened) and for each set of the tubing head choke, the transient pressure at four measurement points were recorded. For this set of runs, 1 mm ID single nozzle gas-lift injector was used in the experiments and a lift gas injection rate of \( 1.87e^{-4} \) m\(^3\)/s was set in a rotameter while the liquid flow rate was set at 7.7 \( 10^{-4} \) m\(^3\)/s in a speed potentiometer connected to a positive displacement gear pump.

Transient pressure profile recorded simultaneously with the four pressure transducers located in \( L/D = 0 \) (bottomhole), \( L/D = 18.3 \) (operating valve), \( L/D = 36.7 \) (unloading valve) and \( L/D = 53.3 \) (tubing head) along the production tubing is shown in Figure 3, where four distinguishable patterns are observed as a consequence of gradually choking at tubing head.

In region A (production choke fully opened) the pressure profile shows peak-to-peak oscillatory behaviour (maximum and minimum) with no periodicity and no similarity in the profiles at the four measurement points along with the production tubing. These oscillations are induced by the expansion, breakage, and coalescence of the gas-lift flowing inside the tubing. By closing the production choke in 50% (region B), the pressure continues to fluctuate in the four measurement points with higher amplitude than in region A and the profile tend to be similar in the four measurement points characterised by a coincidence of the occurrence (periodicity) of the peaks. For 75% closed choke (region C), there is an increase in pressure oscillatory amplitude with a periodicity of the occurrence of peaks in the four measurement points. The measured pressure in the four measurements points shows a similar trend. Further, increment in the choke up to 85% (region D) shows fluctuations of pressure with very low amplitudes compared to the rest conditions observed in regions A, B, and C.

An increase in pressure in the four measurement points along the production tubing height is observed during the gradual choking of the system. Additionally, there is a change in pressure behaviour at the four measurements from random peak-to-peak fluctuations to periodic fluctuations of higher amplitudes in regions B and C and an almost stable pressure profile with very low fluctuation in region D.

### Figure 3 Production choke impacting on tubing pressure behaviour in the test section between \( L/D = 36.7 \) to \( L/D = 53.3 \). The choke was gradually closed during the operation from 100% opened (A), 50% closed (B), 75% closed (C) and 85% closed (D) and the GLGIR was set to \( 1.87e^{-4} \) m\(^3\)/s while the liquid flow rate was set at 7.7 \( 10^{-4} \) m\(^3\)/s.

#### 3.2 Estimation of transient solubility of lift gas in liquid along the tubing height

The influence of tubing head choking on lift gas solubility along the production tubing is estimated based on equation 2. The trend noticed in Figure 4 reflects the equation 2 for a constant temperature, a solubility of the gas is directly propositional to pressure. This is proved by comparing Figure 3 with Figure 4. The two figures, show similar profiles during tubing head choking.
3.3 Impact of surface choking on bubbles size and fluid flow regime transition

We examine the effect of restricting the outlet flow conditions on flow patterns occurring in the last test section in-between length to diameter ratio $L/D = 36.7$ to $L/D = 53.3$ of the production tubing. The experiments were performed by varying (closing) gradually the production choke at the outlet from fully opened 100%, to partially closed 85%. For this set of run, 1 mm ID single nozzle gas-lift injector was used for this experiments and the GLGIR of $1.87e^{-4} m^3/s$ was set at gas regulator valve connected to a rotameter for constant liquid flow rate of $7.7e^{-6} m^3/s$.

Videos in slow motion were obtained and analysed using a CASIO Exilim 200 high speed camera with resolution of $640 \times 480$ at 120 frames per second (fps). The sequence of JPEG format images of the two phases flowing vertically upward were obtained by converting the slow motion MOV videos files to JPEG format images using a conversion utility software (DVDVideoSoft Free studio available online (https://www.dvdvideosoft.com/) and downloaded as open source from the internet. The sequence of images were processed in ImageJ software for estimating the equivalent size of the bubbles along the test sections.

Image sequence of flow regimes observed in the test section in-between $L/D = 36.7$ to $L/D = 53.3$ are presented in Figures 5 for fully opened production choke and 6 for partially closed choke 85% respectively.

As presented in Figure 5, large coalescence cap bubbles with characteristic distorted bullet-like shape at the nose and occupying most of the cross-section of the production tubing end is observed. The bubble is separated by liquid slugs as it flows upward along the tubing and high breakage into tiny bubbles at wake region of the formed Taylor bubble is noticed. In-between $L/D = 36.7$ to $L/D = 53.3$, the maximum perimeter of the Taylor bubble observed is $70.98 \ mm$. In the case of 85% closed choke Figure 5 bubble of irregular shape is observed and with deformation as it flows in the liquid film. There is a drastic reduction of the size of the bubble as it rises upwardly and a maximum size of $35.65 \ mm$ was observed.

Figure 5 Effect of choking on bubble size and fluid flow structure in the test section in between $L/D = 36.7$ to $L/D = 53.3$. The choke was fully opened and the GLGIR was set to $1.87e^{-3} m^3/s$ while the liquid flow rate was set at $7.7e^{-6} m^3/s$.

Figure 6 Effect of choking on bubbles size and fluid flow structure in the test section in between $L/D = 36.7$ to $L/D = 53.3$. The choke was 85% closed and the GLGIR was set to $1.87e^{-5} m^3/s$ while the liquid flow rate was set at $7.7e^{-6} m^3/s$.

The slow motion videos examined shows a drastic reduction of the bubble rise velocity as it approaches the production tubing head and consequent collapse at top of the tubing and surrounding the flowing bubble small bubbles are observed and the vorticity of the liquid film is less perceived. The back pressure effect caused by the choke forces the gas to be dissolved in the liquid film. Surrounding the flowing bubble small bubbles are observed at the vorticity of the liquid film is less perceived. Deceleration of the two phase flow as the choke closes was also observed by Alves et al. (2017) in their investigation on transient churn-annular flows in a long vertical tube. Zhou et al. (2018) observed reduction in acceleration of intruding bubble due to existence of riser–top choking.

3.4 Influence of lift gas injection in pressure instability

The mechanism of wave propagation in the production tubing is investigated taking into account the coupled motion of the two-phase medium (air-water). The liquid flow rate was set to $LFR=7.7e^{-6} m^3/s$ while the gas-lift were injected instantly for 3 seconds by manipulating the flow regulator valve located at (a) $L/D = 18.3$ (operating valve) and (b)$L/D = 36.7$ (unloading valve) along the production tubing. Pressure
transducers located at $L/D = 0.0$, $L/D = 18.3$, $L/D = 36.7$ and $L/D = 53.3$ were used to record the pressure transient at the bottomhole; operating valve; unloading valve and tubing head respectively. The amplitude of the time sequence pressure fluctuation is analysed by plotting the standard deviation of the measured pressure fluctuation (Bhowmick et al., 2014; Johnsson et al., 2000) in $L/D = 0.0$; $L/D = 18.3$; $L/D = 36.7$ and $L/D = 53.3$. The test sections are indicated in Figure 2.

### 3.4.1 Lift gas injected from operating valve located at $L/D = 18.3$

The transient pressure profile in the four remeasuring points were plotted against time and the profile is presented in 7. As shown in Figure 7 three regions are observable: region A before the opening of the regulator valve where there is single phase (water) flowing in the production tubing characterised by natural pressure fluctuations of low amplitude ranging from maximum of 0.323 barG to a minimum of 0.299 barG in $L/D = 0.0$ (bottomhole); 0.186 barG to 0.161 barG in $L/D = 18.3$ (operating valve), 0.0991 barG to 0.0786 barG in $L/D = 36.7$ (unloading valve) and from 0.0142 barG to -0.0103 barG at $L/D = 53.3$ (tubing head) accordingly.

High oscillations of transient pressure with larger amplitude compared to the ones in region A are observed in region B (Pressure profile in this region B is referred to immediately after opening the valve and the gas-lift gets in contact with flowing water). Step-up pressure change was observed in $L/D = 0.0$ at bottomhole from 0.304 barG to a0.385 barG. Similar trend is noticed in operating valve were a step-up from 0.161 barG to 0.185 barG, while a step-down pressure change is noticed in $L/D = 36.6$ from 0.0894 barG to 0.0269 barG and from −0.0288 barG to −0.045 barG for $L/D = 53.3$ respectively.

Region C is characterised by relaxation period of pressure oscillations as a result of close of flow regulator valve where there is a decay in pressure disturbance amplitude and a linear increase of pressure on time in the four measurement points to the level of region A.

As can be scrutinised from Figure 7, there is delay of 3 seconds in pressure fluctuation as a result of gas injection in $L/D = 0.0$ (bottomhole), 2 seconds delay in pressure oscillation in $L/D = 36.7$ and 4 seconds delay in pressure fluctuation in $L/D = 53.3$ respectively. The perturbation of pressure as a result of gas-lift injection into the production tubing is delayed in the four measurement points away from the injection point and has immediate effect at injection point. The time delay might e associated to the wave propagation effect from the point of injection to a point and downward direction along the pipe. As can be noticed when the fluid flowing from the bottomhole contacts with the gas at injection point $L/D = 18.3$ the force of impact of the gas brings about pressure fluctuation.

The amplitude of the time sequence pressure fluctuation is analysed by plotting the standard deviation of the measured pressure fluctuation in $L/D = 0.0$; $L/D = 18.3$; $L/D = 36.7$ and $L/D = 53.3$. A comparison is made in the three regions A(before opening the valve), B(flow regulator valve opened for 3 seconds ) and C (after closing the valve) as illustrated in Figure 8. As observed, the influence of gas volume fraction is noticed along the production tubing and this affects the wave velocity. Miyazaki et al. (1971) observed step-up pressure disturbance during transient response on propagation of pressure wave in air-water two phase system. This investigation has shown similar trend of pressure response as a result of variation of gas volume fraction inside the tubing.

### Figure 7

Time sequence of the pressure fluctuation due to instantly injection of gas-lift for 3 seconds by manipulating the flow regulator valve located at (a) $L/D = 18.3$ (operating valve) and (b) $L/D = 36.7$ (unloading valve) along the production tubing . The LFR was set to LFR=$7.7e^{-4}$ m$^3$/s while the gas-lift was injected from $L/D = 18.3$ (operating valve)instantaneously for 3 seconds and closed afterward. The pressure profile were recorded in the four measurement points along the production tubing.

Huang et al. (2005) investigated experimentally the characteristic of pressure wave propagation in bubbly and slug flow and noticed that the pressure wave intensity decrease exponentially with distance. This observation agrees with our investigation presented in Figures 7 and 10 respectively.

Lower standard deviation is observed in region A ranging from a maximum of 0.00789 barG to a minimum of 0.005095 barG while in region B there is high standard deviation ranging from 0.04418 barG to 0.04052 barG and in region C a decay of standard deviation is noticed. The standard deviation increases 2 times from region A to region B and decreases 2 times from region B to region C in $L/D = 0.0$ (bottomhole), while in $L/D = 18.3$ the standard deviation is increased 7 times from region A to region B and decreases 2 times from region B to region C, in $L/D = 36.7$ the standard deviation increases 7 times from region A to region B and has reduction ratio of 4 from region B to region C. In $L/D = 53.3$ the standard deviation increases 3 times from region A to region B and decreases 2 times from region B to region.

Costigan and Whalley (1997) observed a rarefaction wave traveled from the bottom of the cylindrical pipe to the top when studying the speed of sound in air-water flow in vertical upward flows . They argued that amplitude of successive reflections decayed rapidly as the energy of wave was dissipated.
The fluctuation ratios of the amplitude oscillations from region A to C is shown in Figure 9 where the standard deviation increases 6 times from region A to region B and decreases 2 times from region B to region C in $L/D = 0.0$ (bottomhole), while in $L/D = 18.3$ the standard deviation is increased 7 times from region A to region B and decreases 2 times from region B to region C, in $L/D = 36.7$ the standard deviation increases 7 times from region A to region B and has reduction ratio of 2 from region B to region C. In $L/D = 53.3$ the standard deviation increases 5 times from region A to region B and decreases 2 times from region B to region C.

Figure 9 Standard deviation ratios of the amplitudes oscillation as function of $L/D$ from region A to region B and from region B to region C. Blue solid line represents the increase ratio of the amplitude of pressure oscillation from region A to region B and the red solid line shown the reduction ratio of the amplitude of pressure oscillation from region B to region C.

3.4.2 Lift gas injected from unloading valve located at $L/D = 36.7$

Plots of time series fluctuation of pressure in the four measurement points $L/D = 0.0$; $L/D = 18.3$; $L/D = 36.7$ and $L/D = 53.3$ are illustrated in Figure 10. As observed in Figure 10 three regions are distinguishable: region A corresponding to the period before opening the valve, region B which corresponds to the period in which the injection valve was opened instantaneously for 3 seconds and region C which corresponds to the period in which the valve is closed.

Region A is typified by natural pressure fluctuations of low amplitudes ranging from maximum of 0.326 barG to a minimum of 0.301 barG in $L/D = 0.0$ (bottomhole); 0.191 barG to 0.168 barG in $L/D = 18.3$ (operating valve), 0.106 barG to 0.0816 barG in $L/D = 36.7$ (unloading valve) and from 0.02 barG to -0.0073 barG at $L/D = 53.3$ (tubing head) respectively. The low oscillation in pressure is confirmed by low standard deviation of the amplitude that range from 0.0069 barG in $L/D = 0.0$, 0.0060 barG in $L/D = 18.3$, 0.0085 in $L/D = 36.7$ and 0.0086 barG in $L/D = 53.3$. The standard deviation plot of the pressure fluctuation in four points ($L/D = 0.0$; $L/D = 18.3$; $L/D = 36.7$ and $L/D = 53.3$) along the production tubing is presented in Figure 11.

Figure 10 Time sequence of the pressure fluctuation due to injection of gas-lift along the production tubing. The LFR was set to $LFR = 7.7e^{-6} m^3/s$ while the gas-lift was injected from $L/D = 36.7$ (unloading valve) instantaneously for 3 seconds and closed afterward. The pressure profile were recorded in the four measurement points along the production tubing.

Region B is characterised by high oscillations of the time series pressure with larger amplitude compared to the ones in region A. Step-up pressure change was observed at measurement points $L/D = 0.0$, $L/D = 18.3$ and in $L/D = 36.7$. The increase in pressure amplitude reaches a maximum values of 0.3615 barG in $L/D = 0.0$, 0.2092 in $L/D = 18.3$ and 0.1402 in $L/D = 36.7$ while a step-down pressure change is noticed in $L/D = 53.3$ with a minimum value of -0.1275 barG.

Region C is characterised by relaxation period of pressure oscillations as a result of close of flow regulator valve where there is a decay in pressure disturbance amplitude and a linear increase of pressure on time in the four measurement points to the level of region A. The restoring time ( time required to restore the pressure to the level of pressure in region A) is about 32 seconds.

The time response to the disturbance imposed by the addition of gas into the production tubing is different in the four measurement points as can be seen in Figure 10. At injection point $L/D = 36.7$ the effect is immediately, whereas at points $L/D = 0.0$, $L/D = 18.3$ and $L/D = 53.3$ here is a delay of 2 seconds. The same happens after the closing of the valve where the recovery of pressure is delayed in 2 seconds at
points $L/D = 53.3$ far away the point where the gas-lift has been injected ($L/D = 36.7$).

As can be observed in Figure 11 the standard deviation is lower in A ranging from a maximum of 0.0086 barG to 0.0682 barG and in region B there is high standard deviation ranging from 0.0474 barG to 0.0682 barG and in region C a decay of standard deviation is noticed. The fluctuation ratios of the amplitude oscillations from region A to C is presented in Figure 12 where the standard deviation increases 9 times from region A to region B and decreases 2 times from region B to region C in $L/D = 0.0$ (bottomhole), while in $L/D = 18.3$ the standard deviation is increased 10 times from region A to region B and decreases 2 times from region B to region C in $L/D = 36.7$ the standard deviation increases 8 times from region A to region B and has reduction ratio of 2 from region B to region C. In $L/D = 53.3$ the standard deviation increases 5 times from region A to region B and decreases 2 times from region B to region C.

Figure 11 Standard deviation plot of the pressure fluctuation in four points along the production tubing for gas-lift injected at $L/D = 36.7$.

Figure 12 Standard deviation ratios as function of $L/D$ from region A to region B and from region B to region C. Blue solid line represents the increase ratio of the amplitude of pressure oscillation from region region A to region B and the red solid line shown the reduction ratio of the amplitude of pressure oscillation from region B to region C.

4 Conclusions

Transient nature of gas-lift oil producing well has been reproduced experimentally in the multiphase laboratory scale rig. Tubing head choking was replicated in this investigation in order to study its effect on gas-lift stability (a) evaluating its impact on bottom hole pressure, operating valve pressure and unloading valve pressure oscillation and (b) investigating its influence on flow patterns transition occurring in production tubing.

It was found that increasing the choke a transition from random peak-to-peak oscillation of pressure between an average value to a cyclic periodic oscillation is observed and this behaviour is accompanied by increase in pressure along the production tubing. Production choke impacting on bubble size and flow regime transition was investigated and it was observed that there is a drastic reduction of the size of the bubble as their flow upwardly with a maximum perimeter of 35.65 mm when the choke is $85\%$ closed. The slow motion videos examined show a drastic reduction of the bubble rise velocity as their approach the production tubing head and consequent collapse at top of the tubing. Surrounding the flowing bubbles small bubbles are observed and the vorticity and turbulence of the liquid film and are less perceived. The flow regime with choke closed at $85\%$ is similar to bubbly flow. The back pressure effect caused by the choke forces the gas to be dissolved in the liquid film.

The momentary stability observed in the production tubing associated with increasing the tubing head choke is strongly related to bubbles size devolution and increase in lift gas solubility along the production tubing height cause by increase of backpressure. Tubing head choke acts as a pressure stabiliser and fluid flow regime transition postponer.

It can be concluded from this investigation that the use of tubing head choke in stabilising flow in gas-lift wells has to be conjugated with knowledge and understanding of fluid flow behaviour along the production tubing during gas-lift operations. The influence of surface choking and fluid flow regime transition on liquid production rate will be investigated as part of future research.

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References


